# Meeting 3 – 19/10/18

Members in Attendance:  
Fraser  
Daniel  
Koushik  
Steven  
Dennis   
Yana   
  
On the agenda:  
Fixing communications   
Consolidation of code  
Progress updates

### Progress updates:

Fraser: Updates to GUI to accommodate for Assignment 3 specifications e.g. snapshot of board  
Daniel: Robot studio code updates for linking  
Koushik: Camera calibration functions  
Steven: MATLAB communications: hexadecimal for data transmission, delimiters  
Dennis: Path finding basics down  
Yana: Robot studio CAD progress: up to block interactions

TODO:  
- comms: strings being sent and not being processed on ROBOT  
- comms: delimiter processing on MATLAB  
- comms: delimiter processing on ROBOT  
- ROBOT: send back a robot busy status   
- vision  
- basic movement  
- working simulation!!!!!!!!  
- GUI: manual block addition